



# ***Design of a sample approach mechanism for a metrological AFM***

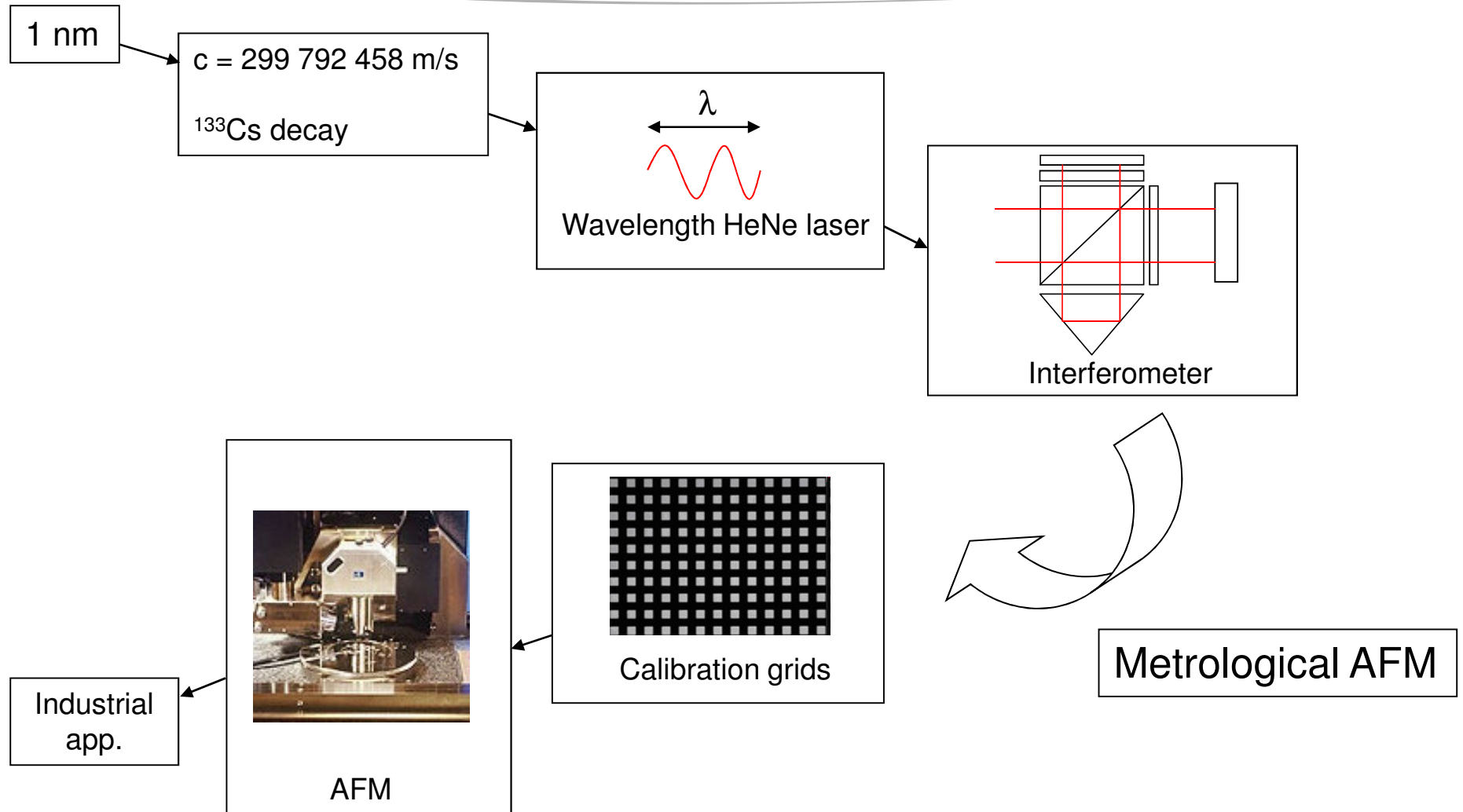
Nanoscale 2010 Seminar  
Brno, Czech Republic

Jan Piot  
K.U.Leuven – Division PMA

# Overview

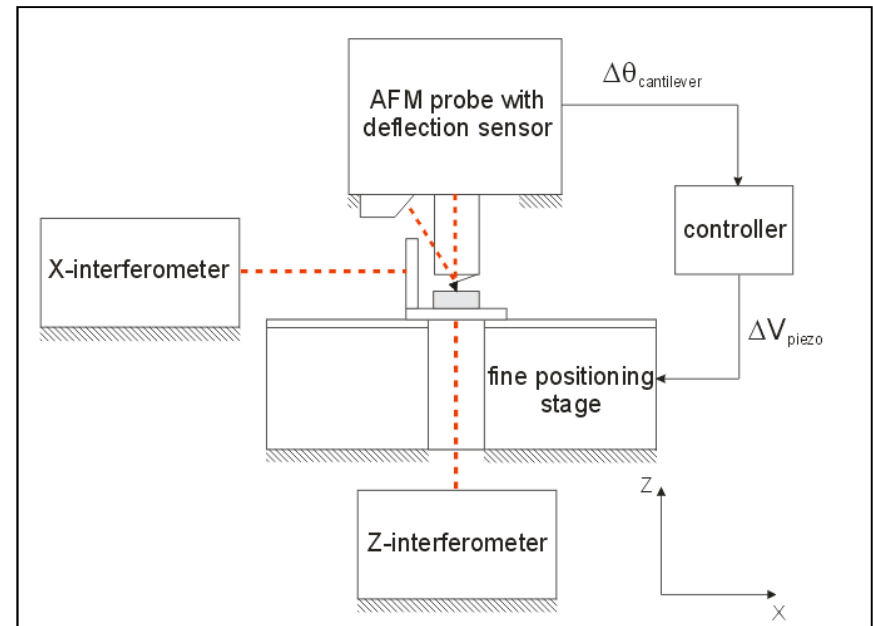
- Introduction
- General layout metrological AFM
- Design sample approach mechanism
- Experimental results
- Simulation
- Conclusions

# Introduction



# Introduction

- Three orthogonal interferometers
- Nanostage scans in XY-plane
- AFM-probe detects deflection
- Nanostage zeroes signal
- Map of Z as function of X and Y



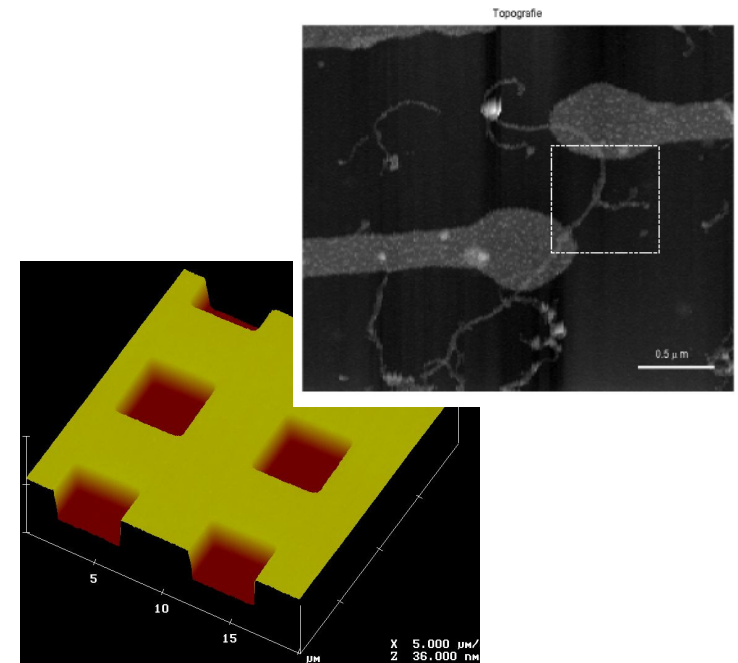
## Advantages:

- Directly traceable measurements
- Measures local values

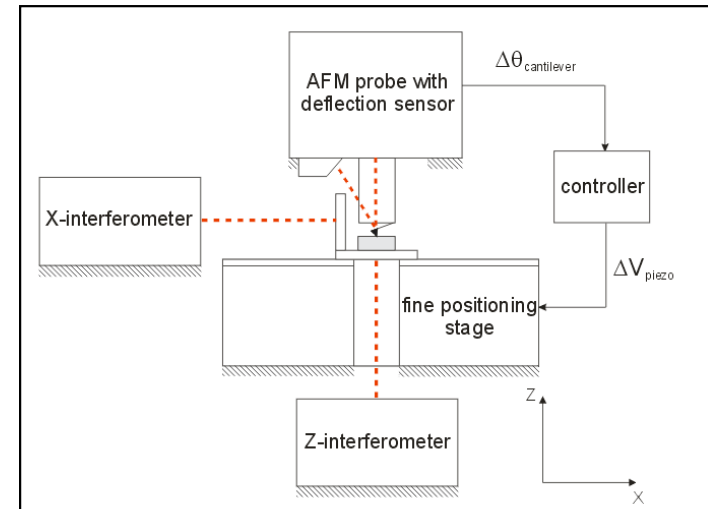
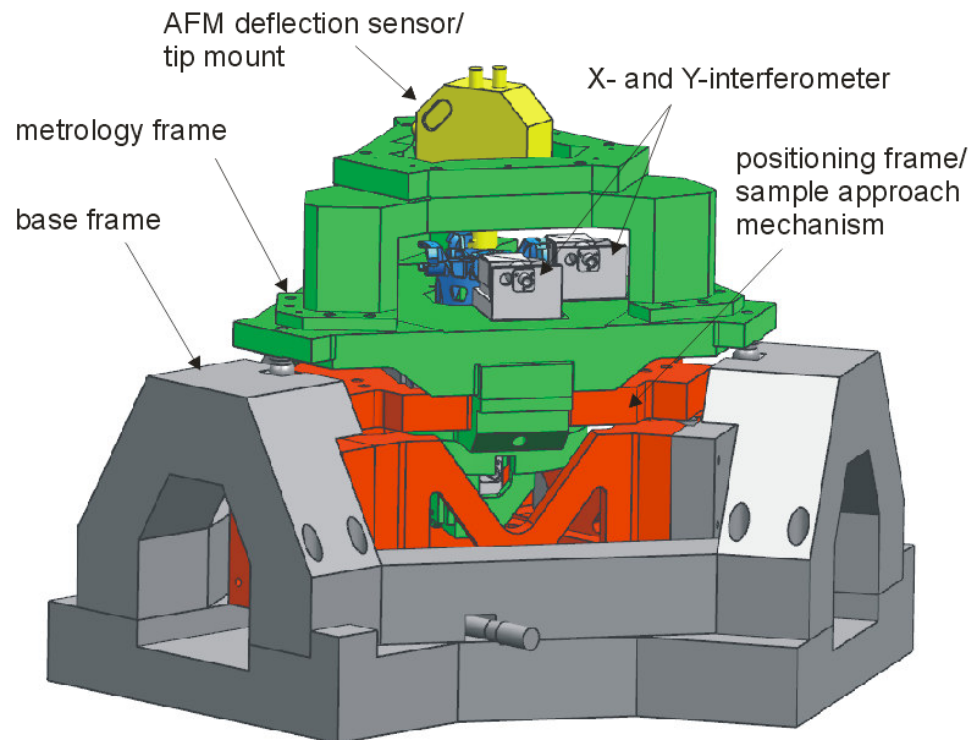
# Introduction

## Project goal

- Calibration device for traceable measurements
- Designed for FPS Economy, SMEs, Self-employed and Energy
- Specifications:
  - ✓ 1 nm accuracy
  - ✓ stroke of  $100\text{ }\mu\text{m} \times 100\text{ }\mu\text{m} \times 100\text{ }\mu\text{m}$
  - ✓ calibration nanogrids
  - ✓ direct measurements

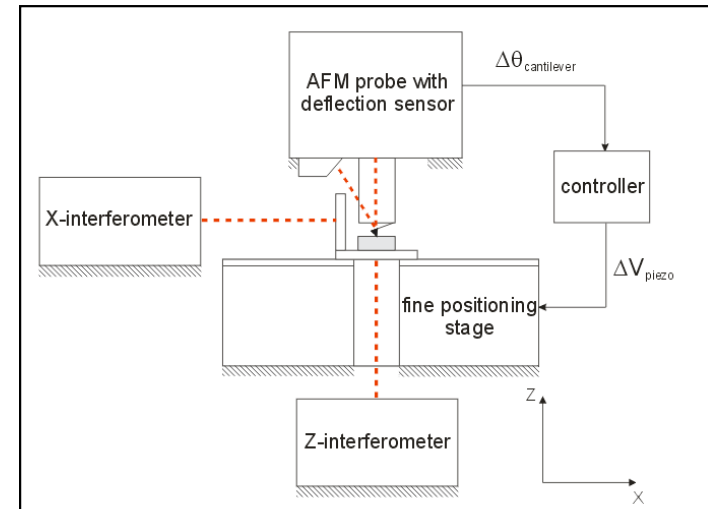
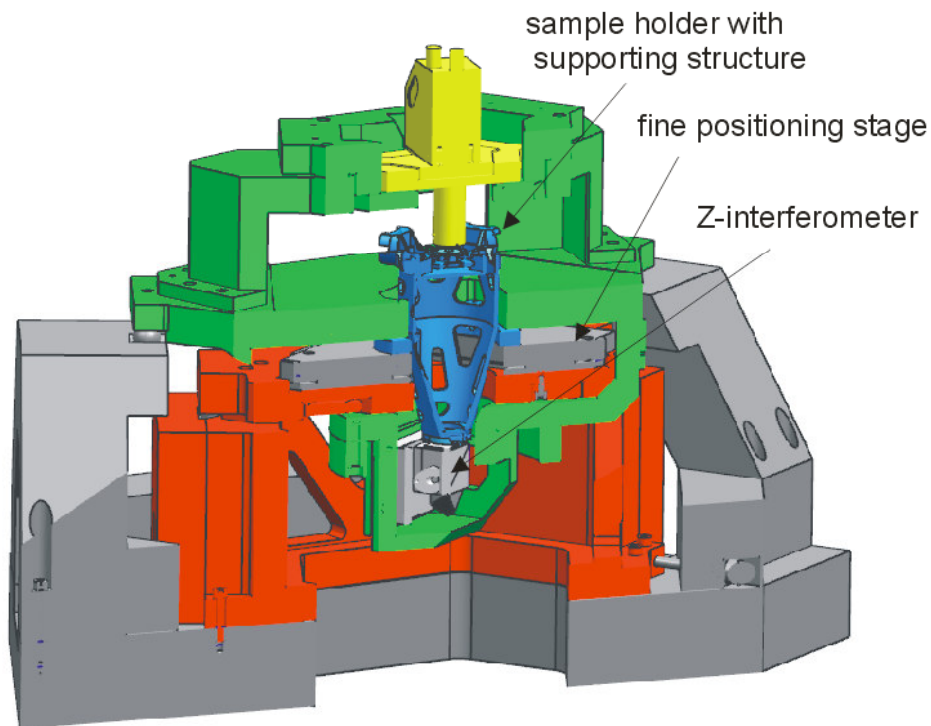


# General layout: frame



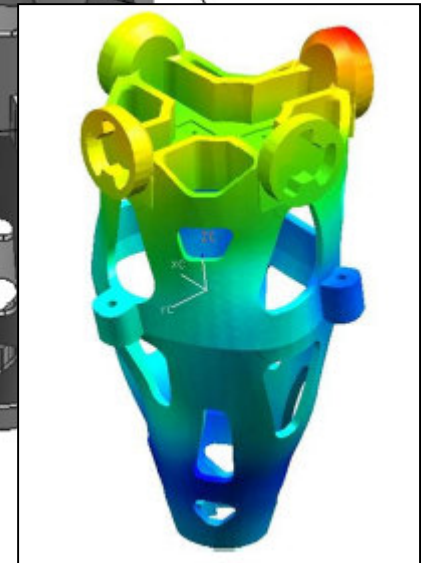
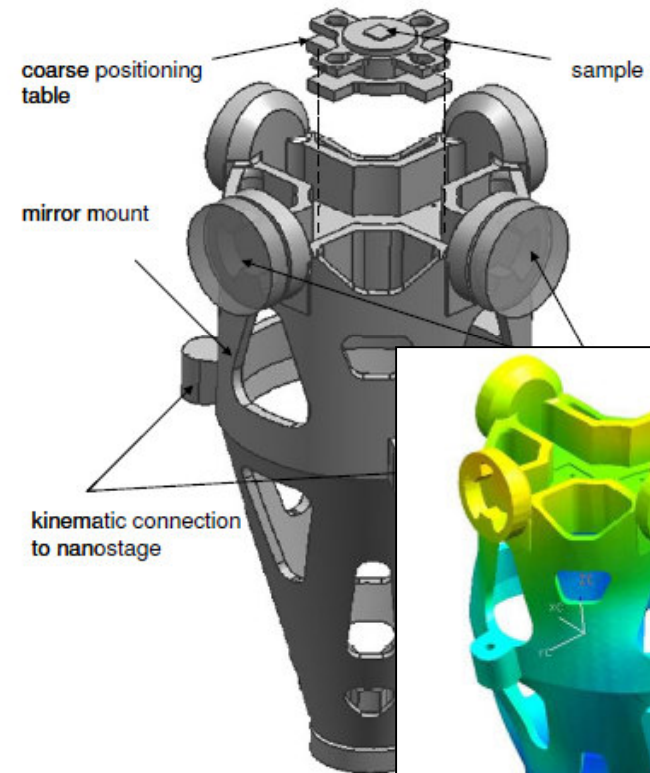
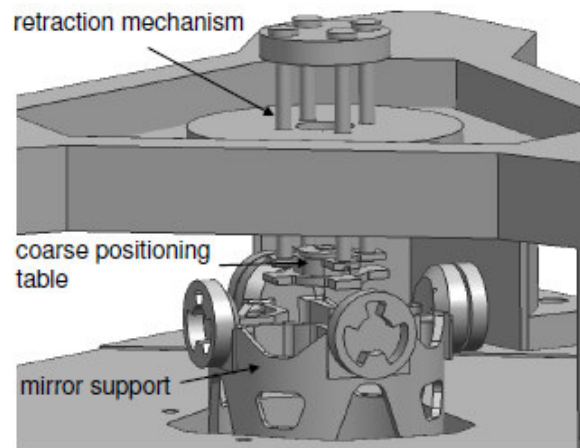
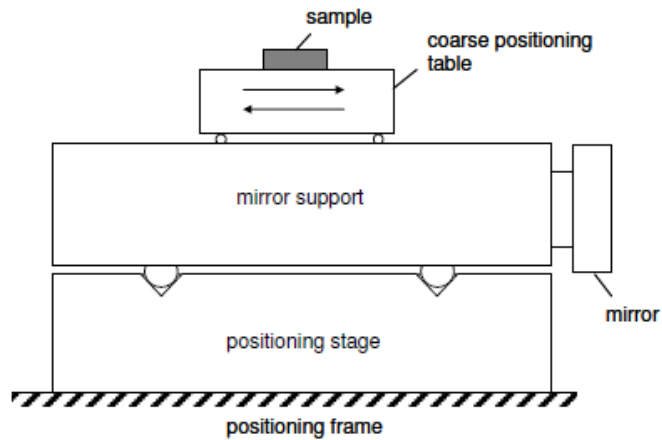
- Materials choice for minimum thermal drift
- Thermal conductivity
- Separated force loop

# General layout: frame



- Materials choice for minimum thermal drift
- Thermal conductivity
- Separated force loop

# Sample holder





# ***Sample approach mechanism***

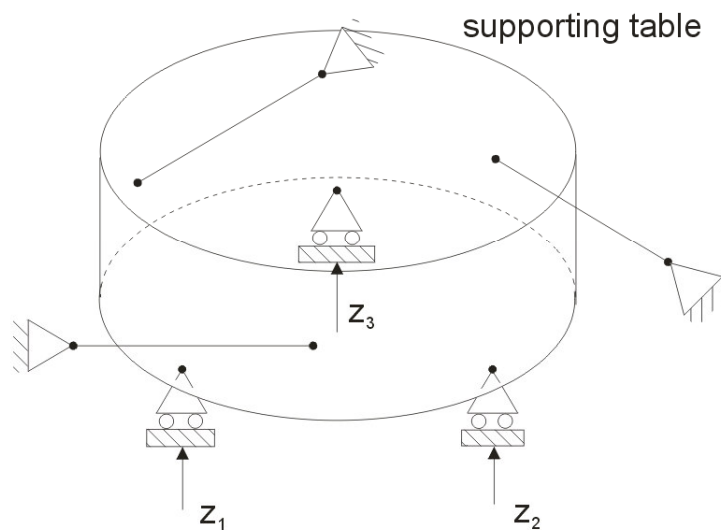
## ➤ Functions

- Approach sample to probe tip
- Align sample to frame

## ➤ Requirements

- Mechanical stability
- Thermal stability
- Safe approach
- Sufficient alignment possibilities

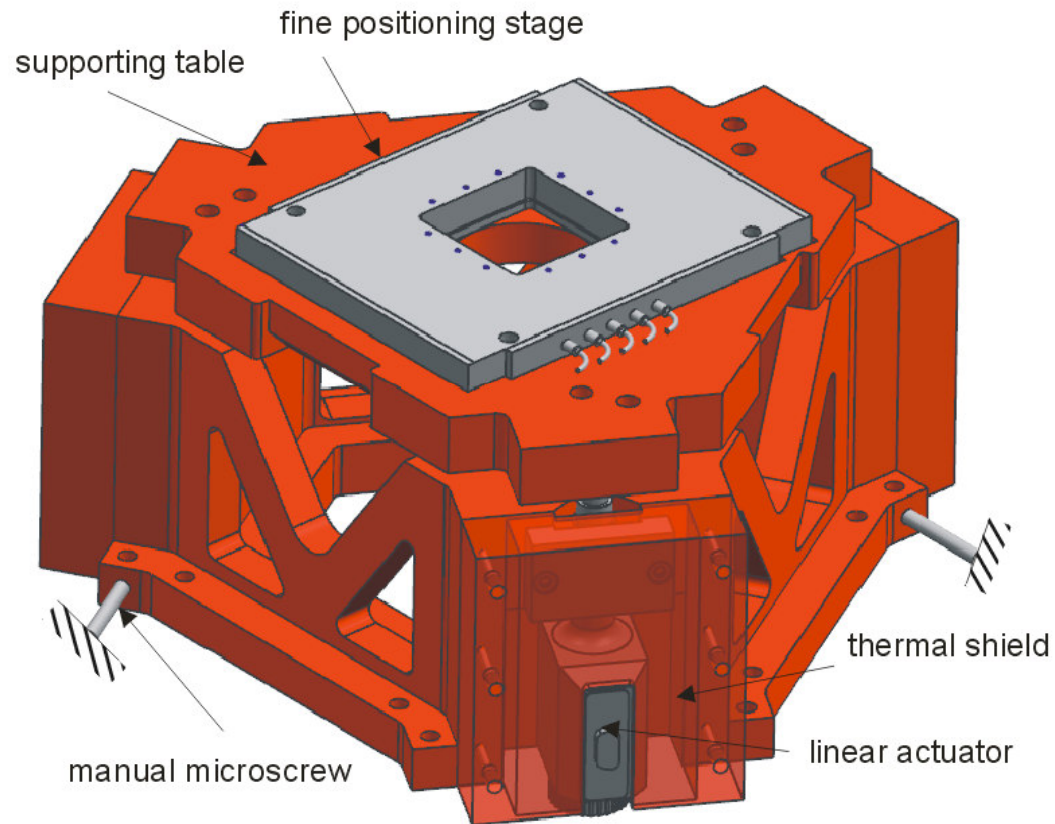
# Sample approach mechanism



## Properties

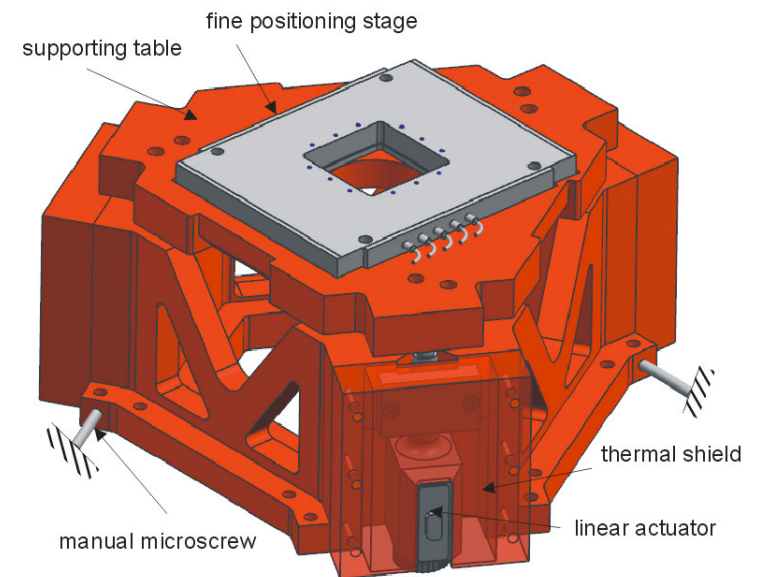
- Compact/integrated design
- Kinematic design
- Careful design of rods
  - Self-locking actuators
  - Low stress during expansion
  - Good heat conductivity
  - Symmetry
- Alignment possibilities
- Safe approach (2 modes)

# *Sample approach mechanism*

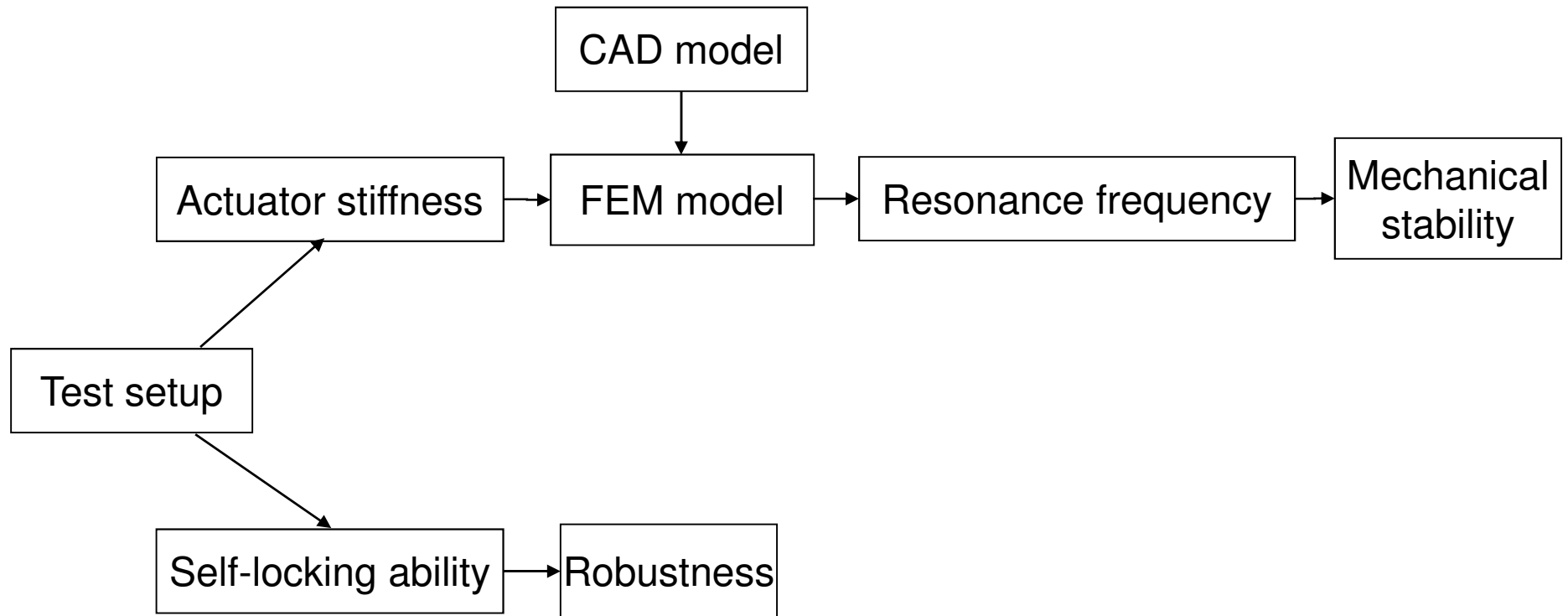


# Sample approach mechanism

Specifications	
Mechanical	<ul style="list-style-type: none"><li>• automated approach</li><li>• 1.3 <math>\mu\text{m}</math> resolution</li><li>• 1 mm stroke</li></ul>
Thermal	<ul style="list-style-type: none"><li>• no heat production during scan</li><li>• fast thermal settling time</li></ul>
Alignment	<ul style="list-style-type: none"><li>• alignment accuracy of 45 arcseconds in X- and Y-directions</li><li>• alignment accuracy of 25 arcseconds in X- and Y-directions</li><li>• rotation range of 0.4 degrees</li></ul>
Robustness	<ul style="list-style-type: none"><li>• safe approach</li></ul>



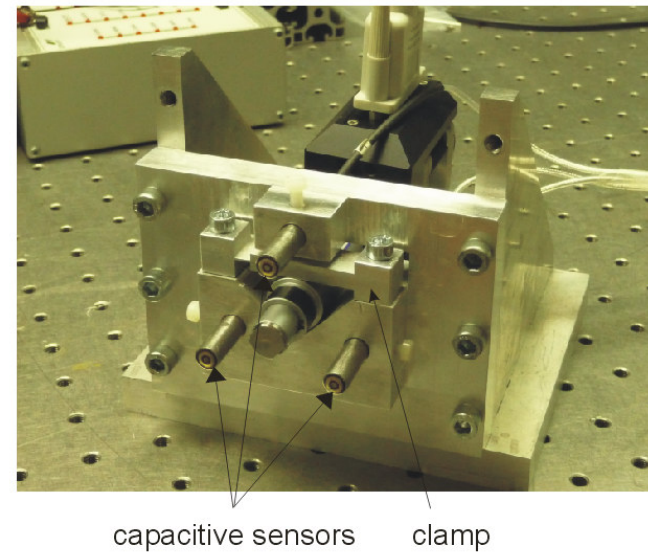
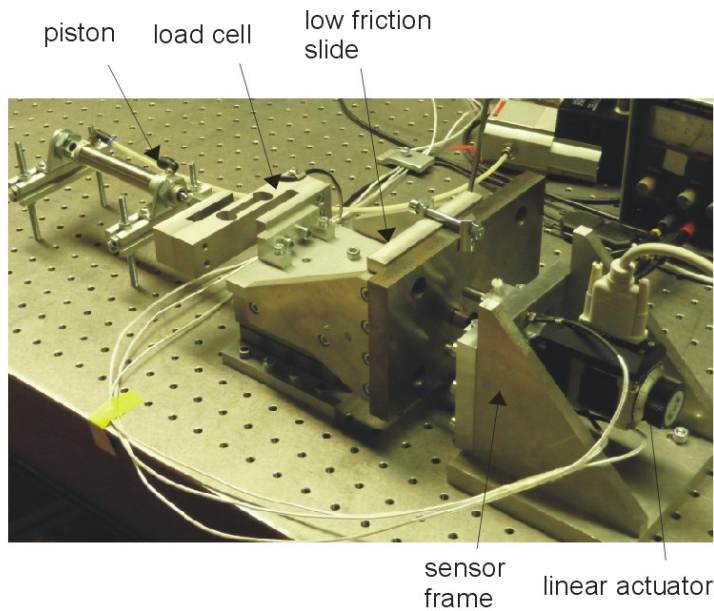
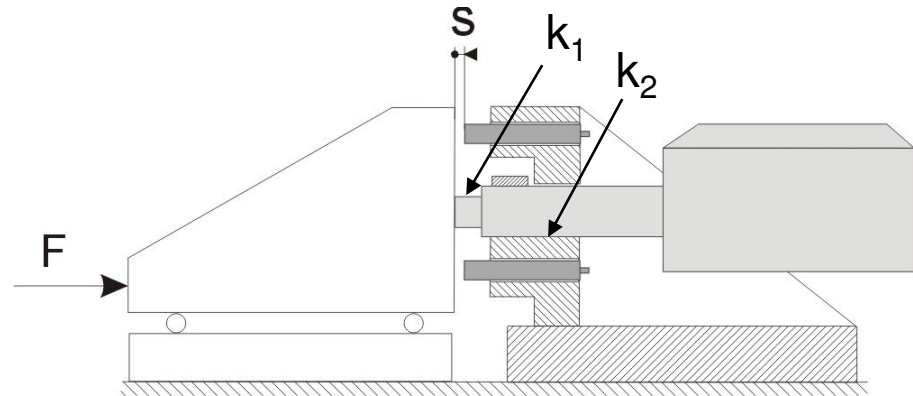
# Experiments





# ***Experiments***

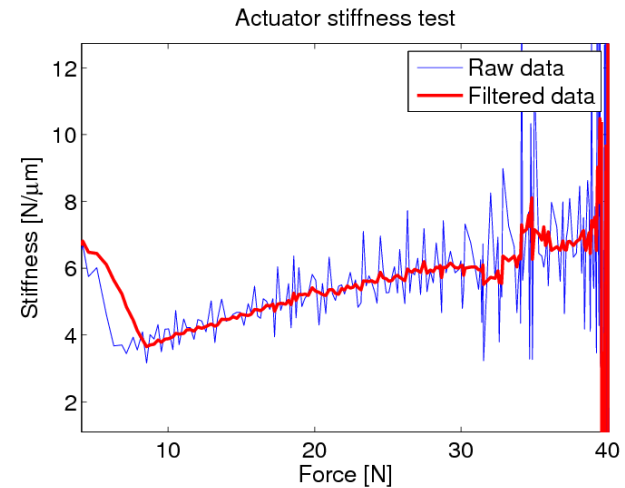
## Stiffness measurement



# Experiments

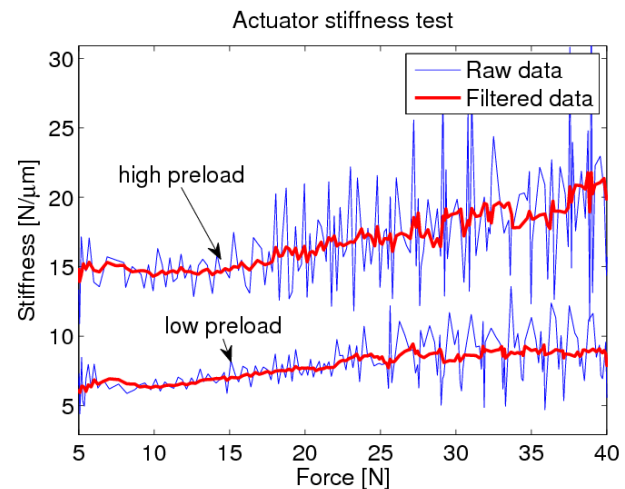
## Result for linear actuator

- Stiffness 4 – 7 N/μm
- Low preload



## Result for microscrew

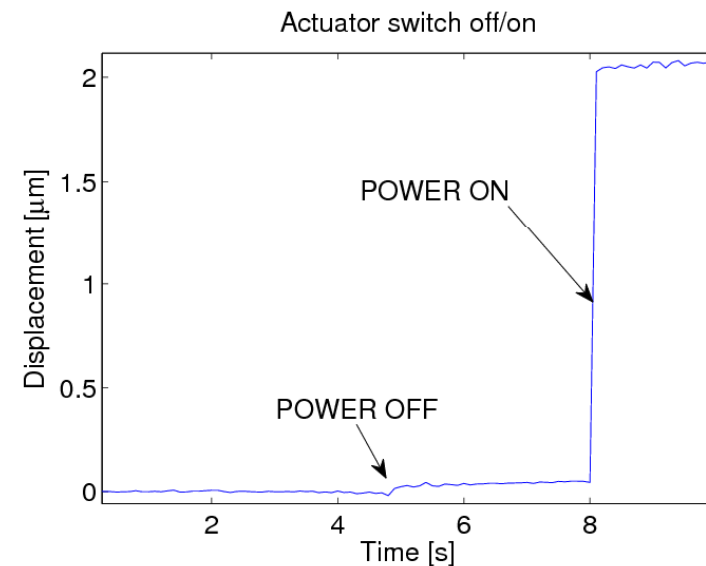
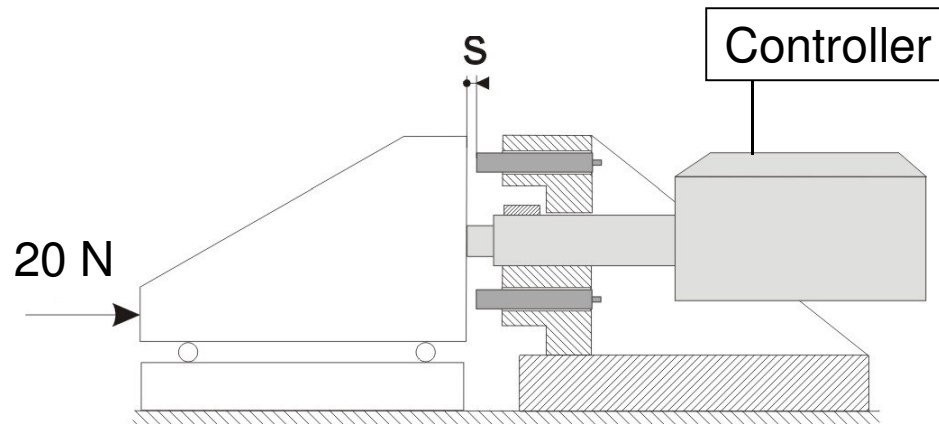
- Higher preload possible
- Same principle
- Low preload: 6 - 9 N/μm
- High preload: 15 – 20 N/μm





# Experiments

## Self-locking behaviour



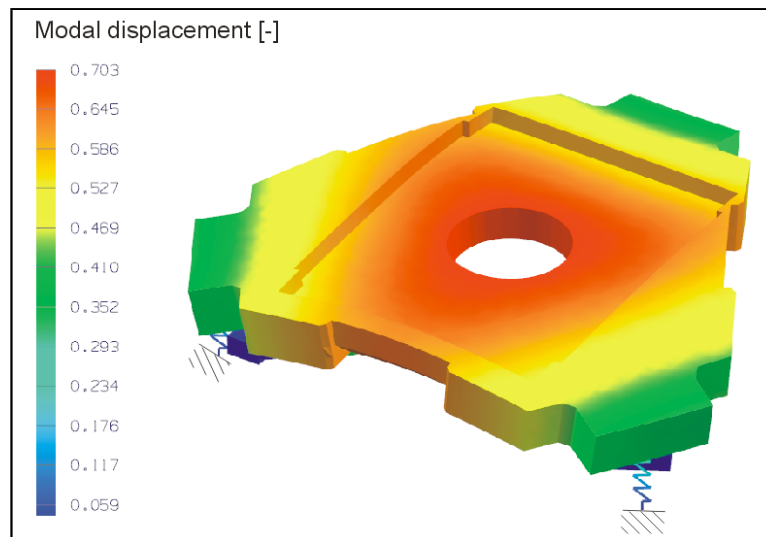
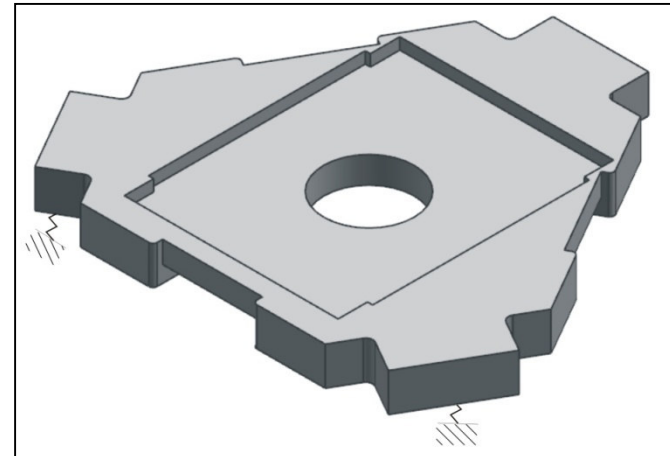
Switch-off: 30 nm  
Switch-on: 2  $\mu\text{m}$



# Simulation

## FEM model

- Supporting plate
- Actuators: equivalent springs
- Unloaded eigenmodes



## Evaluation

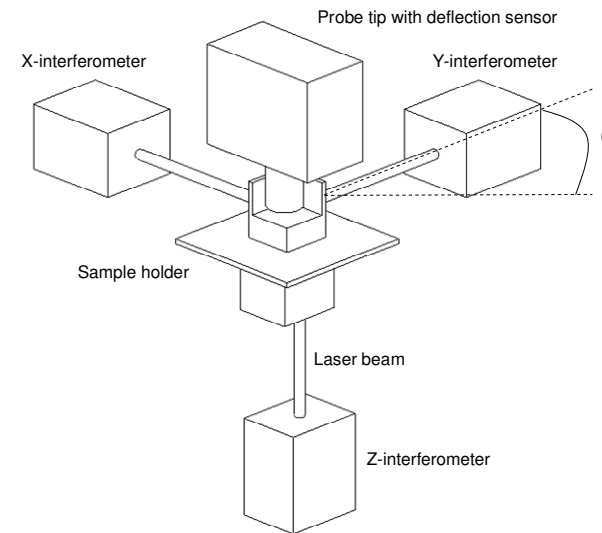
- 395 Hz for 10 N/ $\mu$ m
- High preload: 440 Hz
- Low preload: 285 Hz
- Meets specifications

# Alignment procedure

- Cosine error

$$\theta = 200 \text{ arcsec}$$

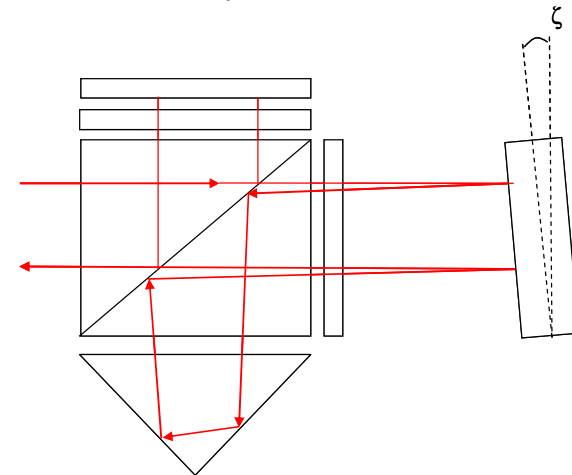
$$U = 0.05 \text{ nm}$$



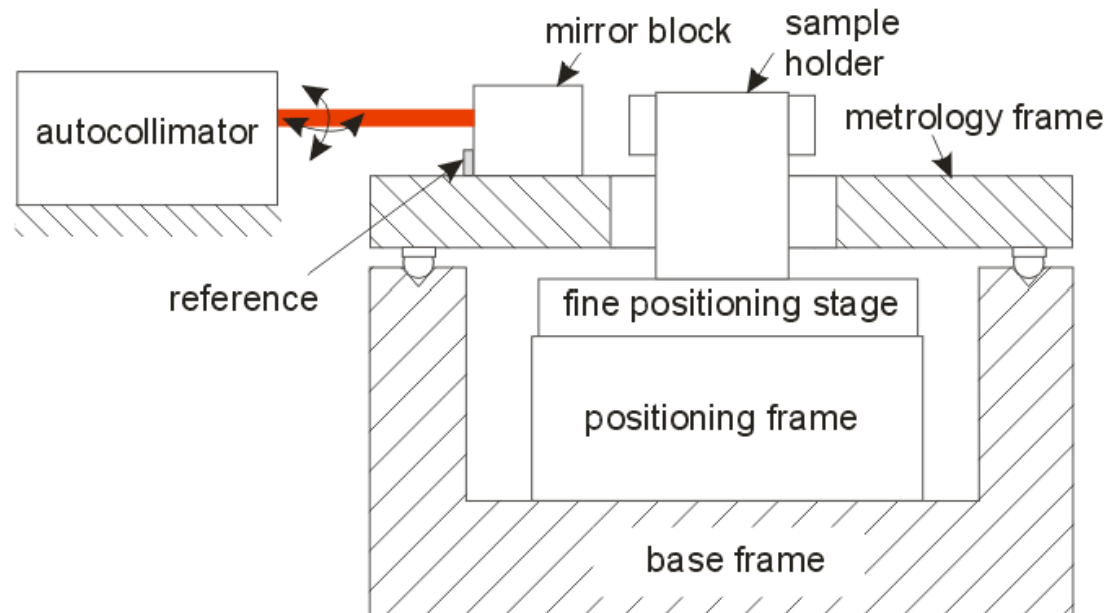
- Mirror tilt error

$$\theta = 200 \text{ arcsec}$$

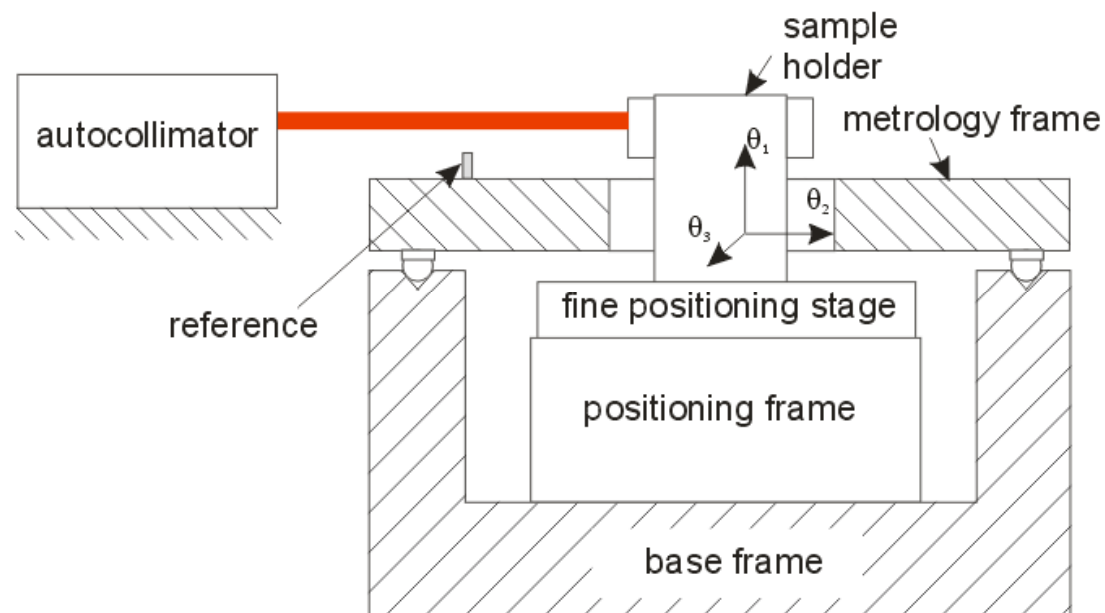
$$U = 0.25 \text{ nm}$$



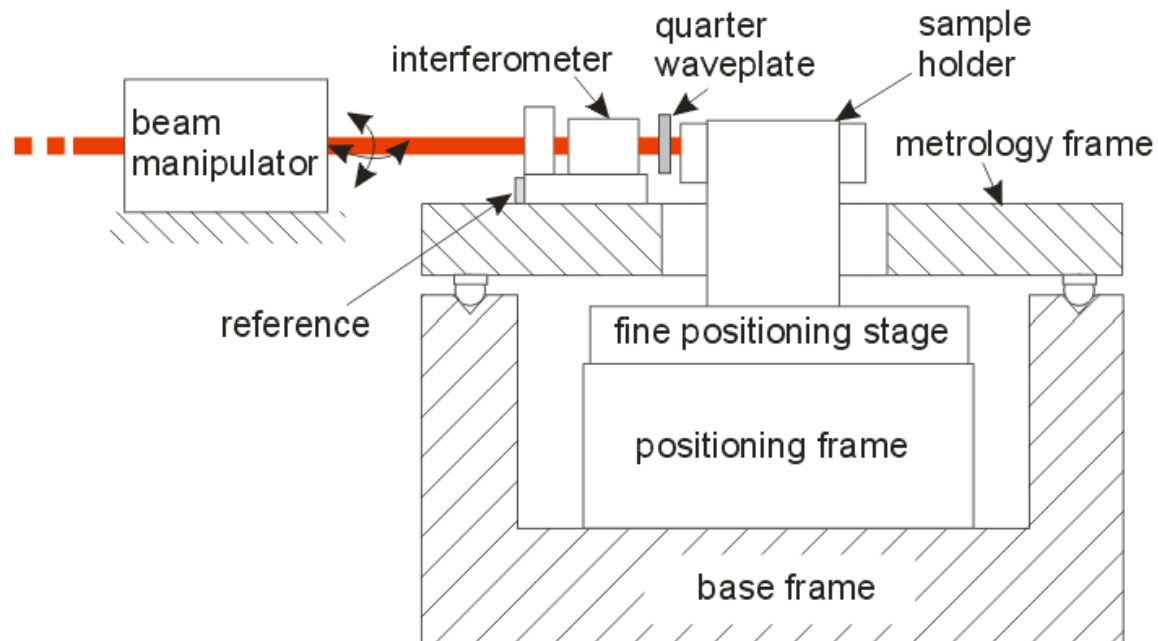
# Alignment procedure



# Alignment procedure



# Alignment procedure



# Conclusion

- Design metrological AFM
- Design sample approach mechanism
  - Mechanical properties
  - Thermal properties
  - Alignment possibilities
- Experiments linear actuator
  - Static stiffness
  - Self-locking ability
- Dynamic stiffness of 395 Hz
- Actuator meets design requirements
- Current work
  - Scanhead thermal design
  - Prototype (half November)
  - Production (beginning 2011)